# ELECTROMAGNETIC INDUCTION <br> AND ALTERNATING CURRENTS 

## MAGNETIC FLUX

Magnetic flux $\left(\Phi_{\mathrm{B}}\right)$ through an area $d \overline{\boldsymbol{s}}$ in a magnetic field $\overline{\boldsymbol{B}}$ is defined as

$$
\Phi_{B}=\int \overrightarrow{\mathbf{B}} \cdot d \overrightarrow{\mathbf{S}}
$$

For an elemental area $d \overline{\mathbf{S}}$ in a magnetic field $\overrightarrow{\mathbf{B}}$, the associated magnetic flux is given by


$$
d \Phi_{\mathrm{B}}=\overrightarrow{\mathbf{B}} . \overrightarrow{\mathrm{S}}=B d S \cos \theta
$$

As magnetic lines of field are closed curves (i.e., monopoles do not exist), total magnetic flux linked with a closed surface is always zero, i.e.,

$$
\oint \overrightarrow{\mathbf{B}} . d \overrightarrow{\mathbf{S}}=0
$$

This law is called Gauss' law for magnetism.

## INDUCED EMF

## FARADAY'S LAWS OF ELECTROMAGNETIC INDUCTION

## Law I:

Whenever there is a change of flux linked with a circuit, or whenever a moving conductor cuts the flux, an emf is induced in it.

This phenomenon is called electromagnetic induction and the emf, induced emf. If the circuit is closed the current which flows in it due to induced emf is called induced current.

## Law II:

The magnitude of induced emf is equal to the rate of change of flux, i.e.,

$$
E=\left|\frac{d \Phi}{d t}\right|
$$

The direction or the sense of the induced emf (or induced current) is given by Lenz's law.

## LENZ's LAW

The effect of the induced emf is such as to oppose the change in flux that produces it.

$$
\mathrm{E}=-\frac{d \Phi}{d t}
$$

Negative sign indicates towards the Lenz's law.

## Induced Charge Flow

When a current is induced in the circuit due to the flux change, charge flows through the circuit. The net amount of charge which flows along the circuit is given as:

$$
i=\frac{\mathrm{E}}{R}=-\frac{1}{R} \frac{d \Phi}{d t}
$$

Thus, the induced charge is independent of the manner and time in which the flux changes. However, the induced emf and current depend on time.

## Motional EMF

The induced emf,

$$
\mathrm{E}=\frac{\Delta \Phi}{\Delta t}=B l v \sin \theta
$$

In vector notation $\mathrm{E}=\int(\overrightarrow{\mathbf{v}} \times \overrightarrow{\mathbf{B}}) d \overrightarrow{\mathbf{L}}$

## Rotating Coil in Magnetic Field

Induced emf can be produced by changing the orientation of a coil respect to the magnetic field.

$$
\Phi=N B S \cos \omega t
$$

Where $N$ is the number of turns $S$ is the area of the coil, $\omega$ is the angular velocity of rotation.

## SELF-INDUCTANCE

It is convenient to express the induced emf in a coil in terms of the current flowing through it rather than the magnetic flux through it,

$$
\Phi \propto I \text { or } \quad \Phi=L I
$$

Where, $L$ is a constant of proportionally, called the selfinductance or simply inductance of the coil.

## SELF-INDUCTANCE OF A COIL

If a coil of radius $R$ has $N$ turns, its self-inductance of a coil

$$
\therefore \quad L=\frac{\Phi}{I}=\frac{\mu_{0}}{4 \pi}\left(2 \pi^{2} N^{2} R\right)=\frac{1}{2} \mu_{0} \pi N^{2} R
$$

## ENERGY STORED IN AN INDUCTOR

The total energy stored in inductor is given

$$
\Rightarrow u=\frac{1}{2} L I^{2}
$$

The energy density of a magnetic field in free space
$=\frac{B^{2}}{2 \mu_{0}}$

## L-R CIRCUIT

(A) Growth of Current

$$
I=I_{0}\left(1-e^{-t / \tau}\right) \text { with } I_{0}=\frac{E}{R} \quad \text { and } \quad \tau=\frac{L}{R}
$$

Here, $I_{0}(=E / R)$ is the final value of current $I$ at $t=\infty$, and the quantity $\tau(=L / R)$ is a constant having dimensions of time. $\tau$ is called time constant of the circuit.

At $t=\tau$, the current is

$$
I=I_{0}\left(1-e^{-1}\right)=0.63 I_{0}
$$

Thus, in one time constant, the current reaches $63 \%$ of the maximum value

## (B) Decay of Current

$$
I=I_{0} e^{\frac{-\mathrm{Rt}}{\mathrm{~L}}}=I_{0} e^{-t / \tau}
$$

Where $\tau=L / R$ is the time constant of the circuit.
We see that the current gradually decreases as time passes. At $t=\tau$,

$$
I=I_{0} / e=0.37 I_{0}
$$

The current reduces to $37 \%$ of the initial value in one time constant, i.e., $63 \%$ of the decay is comlete.


## MUTUAL INDUCTION

The appearance of an induced emf in one circuit due to changes in the magnetic field produced by a nearby circuit is called mutual induction.

Let the current through the primary winding at any instant be $I_{1}$. Then the magnetic flux linking with the secondary winding,

$$
\Phi_{2} \propto I_{1} \quad \text { or } \quad \Phi_{2}=\mathrm{MI}_{1}
$$

Thus, the induced emf in the secondary is given as

$$
\mathrm{E}_{2}=\frac{d \Phi_{2}}{d t} \quad \text { or } \quad \mathrm{E}_{2}=M \frac{d I_{1}}{d t}
$$

Where, $M$ is the constant of proportionally, called the coefficient of mutual induction,

The SI unit of mutual inductance is henry. We may define mutual inductance $M$ as follows:

The mutual inductance $M$ of two colds having self-inductance $L_{1}$ and $L_{2}$ is given by

$$
M=k \sqrt{L_{1} L_{2}}
$$

Where $k$ is a constant called coefficient of coupling. For tight or close coupling, $k=1$, and so $M=\sqrt{L_{2} L_{2}}$. For loose coupling $0<k<1$, and hence $M<\sqrt{L_{1} L_{2}}$.

## Grouping of Coils

(A)Coils in Series

If two coils of inductances $L_{1}$ and $L_{2}$ are connected in series with coefficient of coupling
$k=0$, then potential divides, but the current remains same,

$$
e=e_{1}+e_{2} \quad \text { or } \quad L_{\mathrm{s}} \frac{d I}{d t}=L_{1} \frac{d I}{d t}+L_{2} \frac{d I}{d t}
$$

$\therefore \quad L_{S}=L_{1}+L_{2}$

## (B) Coils in Parallel

In parallel combination, the current divides, but the voltage remains the same,

$$
\begin{array}{ll} 
& I=I_{1}+I_{2} \Rightarrow \quad \frac{d I}{d t}=\frac{d I}{d t}+\frac{d I_{2}}{d t} \\
\therefore \quad \frac{e}{L_{\mathrm{P}}}=\frac{e}{L_{1}}+\frac{e}{L_{2}} & \quad\left[\text { as } e=L \frac{d I}{d t}\right] \\
\text { or } \quad & \frac{1}{L_{\mathrm{p}}}=\frac{1}{L_{1}}+\frac{1}{L_{2}}
\end{array}
$$

## ALTERNATING CURRENT

$I=I_{\max } \sin \omega t$
Where, $I$ is the value of current at time $t$ and $I_{\max }$ is the maximum value of the current and $\omega$ is the angular frequency ( $=2 \pi f$, f being frequency).

## Different Forms of a.c. emf

The variation of A.C. quantity is sinusoidal hence can be expressed as:

$$
\begin{aligned}
& e=E_{\max } \sin \omega t \text { as } \omega=2 \pi f, \text { we have } \\
& e=E_{\max } \sin (2 \pi f t) \text { since } f=1 / T, \text { we have } \\
& e=E_{\max } \sin \left(\frac{2 \pi}{T} t\right)
\end{aligned}
$$

## R. M. S. value of a current

. If $I_{1}, I_{2}, I_{3}, \ldots \ldots . . I_{n}$ are instantaneous currents r . m. s. value will be

$$
I_{\max }=\sqrt{\frac{i_{1}^{2}+i_{2}^{2}+\ldots \ldots . .+i_{n}^{2}}{n}}
$$

We can also expresses this value as

$$
I_{\text {r.m.s. }}=I_{\max } / \sqrt{2}=0.707 V_{\max }
$$

Similarly $\quad V_{\text {r.m.s. }}=V_{\max } \sqrt{2}=0.707 V_{\max }$

## Mean or Average Value of an Alternating current

The alternating currents average value is given by

$$
I_{a v}=\frac{2 I_{\max }}{\pi} \text { or } I_{a v}=0.637 I_{\max }
$$

## A. C. Circuit containing Resistance Only (Resistive Circuit)

$$
v=V_{\max } \sin \omega t
$$

And the current $I=\frac{v_{\max }}{R} \sin \omega \mathrm{t}, \quad I_{\text {max }}=\frac{V_{\text {max }}}{R}$
Or $\quad i=I_{\max } \sin \omega t$
This shows that the current and voltage are in phase.
The power in a circuit is given by $P(=V \times I)$
Hence, $\quad P=I_{\max } \sin \omega t \times V_{\max } \sin \omega t$
Or $\quad P=\frac{1}{2} I_{\text {max }} V_{\text {max }}(1-\cos 2 \omega t)$

## A. C. Circuit Containing Inductor Only (Inductive

 Circuit)$$
i=I_{\max } \sin \left(\omega t-\frac{\pi}{2}\right) \quad \text { where } \quad I_{\max }=\frac{V_{\max }}{\omega L}
$$

The quantity $\omega \mathrm{L}$ is called inductive reactance or reactance and denoted by
$X_{L}(=\omega L=2 \pi f L)$.
The power in an inductive circuit is given by

$$
P=-\frac{1}{2} V_{\max } I_{\max } \sin 2 \omega t
$$

As there is no constant term in power expression, hence the average power in a pure inductive circuit is zero. This is called wattles power.

## A. C. Circuit Containing Capacitance Only (Capacitive Circuit)

$$
i=I_{\max } \cos \omega t=I_{\max } \sin \left(\omega t+\frac{\pi}{2}\right)
$$

Where $\quad I_{\text {max }}=\frac{V_{\text {max }}}{(1 / \omega C)}$

The power in the circuit is given by

$$
P=V_{\max } \sin \omega t I_{\max } \cos \omega t \quad=\frac{1}{2} V_{\max } I_{\max } \sin 2 \omega t
$$

Thus the average power consumed in a pure capacitive circuit is zero.

## Resistance and inductance in series A. C. Circuit



The resultant voltage is given by

$$
v=\sqrt{v_{L}^{2}+v_{R}^{2}}
$$

and $i=\frac{v}{\sqrt{R^{2}+X_{L}^{2}}}$
The term $\sqrt{R^{2}+X_{L}^{2}}$ is called impedance of the circuit and denoted by Z (its units are ohm) i.e.

$$
Z=\sqrt{R^{2}+X_{L}^{2}}
$$

Average power in R and L in series circuit when A . C . current passes is given by

$$
P=V_{\text {r.m.s. }} I_{\text {r.m.s. }} \cos \phi
$$

where $\phi$ is the angle by which vector $V$ leads the vector I.

## Resistance and Capacitance in Series A. C. Circuit

The voltage and current vectors are as shown in figure. The voltage and impedance triangles are shown in figure are given as


(a)

(b)

$$
v=\sqrt{v_{R}^{2}+v_{c}^{2}} \text { and } Z=\sqrt{R^{2}+X_{c}^{2}}
$$

where $\quad X_{c}=1 / \omega \mathrm{C}$ is capacitive reactance.

The power consumed $p=v . I=V_{\text {r.m.s. }} I_{\text {r.m.s. }} \cos \square$

## RLC Series A. C. Circuit

A circuit having resistance $R$, inductance $L$ and capacitance $C$ in series with an A. C. source shown in figure.


$$
v=\sqrt{v_{h}^{2}+\left(v_{L}-v_{c}\right)^{2}}
$$

and the impedance is given by

$$
Z=\sqrt{R^{2}+\left(\omega L-\frac{1}{\omega C}\right)^{2}}
$$



## When $\omega \mathrm{L}>1 / \omega \mathrm{C}$

The net reactance $\omega L-\frac{1}{\omega C}$ is positive hence $\phi$ is also positive as a result current will lag behind voltage or voltage leads the current.

## When $\omega \mathrm{L}=1 / \omega \mathrm{C}$

The net reactance is zero hence $\phi=0$ and the voltage and current are in phase and impedance is equal to the resistance.

## When $\omega \mathrm{L}<1 / \omega \mathrm{C}$

The net reactance $\omega L-\frac{1}{\omega C}$ is negative hence $\phi$ is also negative and the current leads the applied emf.

## Series resonance circuit

The effective reactance is inductive or capcitive depending upon $X_{L}>X_{C}$ or $X_{L}<X_{C}$. The inductive reactance $X_{L}$ is directly proportional to the frequency while the capacitive reactance is inversely proportional to the frequency. At certain frequency both reactances become equal and this frequency is called resonance frequency. At resonance frequency

$$
X_{L}=X_{C} \text { or } \omega L=1 / \omega C \text { i.e. }
$$

$$
\omega_{r}=\sqrt{\frac{1}{L C}} \quad \text { or } \quad f_{r}=\frac{1}{2 \pi} \sqrt{\frac{1}{L C}} \mathrm{~Hz}
$$

The current and voltages are in phase as $Z=R$. Such circuits are called acceptor circuits. The ratio of $v_{L}$ or $v_{C}$ with applied
voltage at resonant frequency is called $Q$-factor or voltage magnification and is given by

$$
Q=\frac{1}{R} \sqrt{\frac{L}{C}}
$$

## TRANSFORMERS

The primary winding has $\mathrm{N}_{1}$ turns, and the secondary winding has $\mathrm{N}_{2}$ turns. When the magnetic flux changes because of changing currents in the two coils, the resulting induced emf's are

$$
\begin{aligned}
& \varepsilon_{1}=-N_{1} \frac{d \Phi_{B}}{d t} \quad \text { and } \quad \varepsilon_{2}=-N_{2} \frac{d \Phi_{B}}{d t} \\
& \frac{\varepsilon_{1}}{\varepsilon_{2}}=\frac{N_{1}}{N_{2}} \\
& \frac{V_{2}}{V_{1}}=\frac{N_{2}}{N_{1}} \text { (Terminal voltages of transformer primary and }
\end{aligned}
$$ secondary)

where $V_{1}$ and $V_{2}$ are either the amplitudes or the rms values of the terminal voltages. By choosing the appropriate turns ratio $\mathrm{N}_{2} / \mathrm{N}_{1}$, we may obtain any desired secondary voltage from a given primary voltage.

## Efficiency of a Transformer

In an ordinary transformer, there is some loss of energy due to primary resistance, hysteresis in the core, eddy currents in the core etc. The efficiency of a transformer is defined as

$$
\eta=\frac{\text { output power }}{\text { input power }}
$$

Efficiencies of the order of $99 \%$ can be easily achieved.

